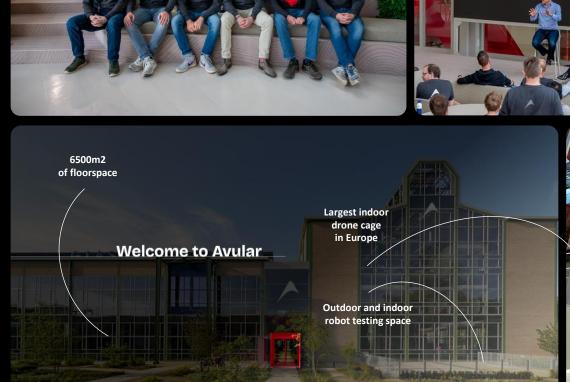


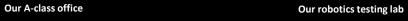




Paul Janssen Avular

Our world-class team



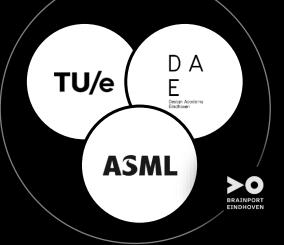




A-location in the smartest region of the world

The birth ground of Philips & ASML and up until now already **9** - time robotic world champion!













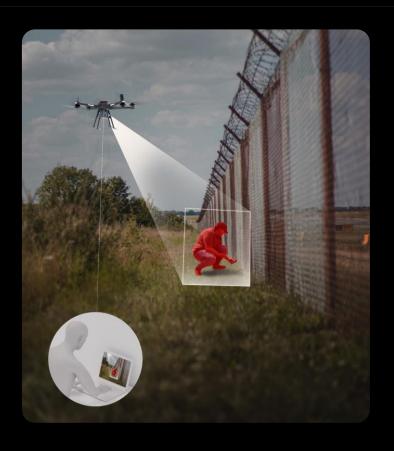
Taylor-made mobile robotic solutions





Robots for Research

Off-the-shelve modular robotic platforms



Drones for Our Security

Off-the-shelve family of drones

A family of mobile robotic systems

Our autonomy hard- & (AI) software blocks at the core

Integration of our autonomy core (hard & software) in other machines



Our Origin, the foundation for new driving applications

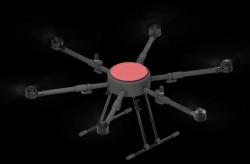


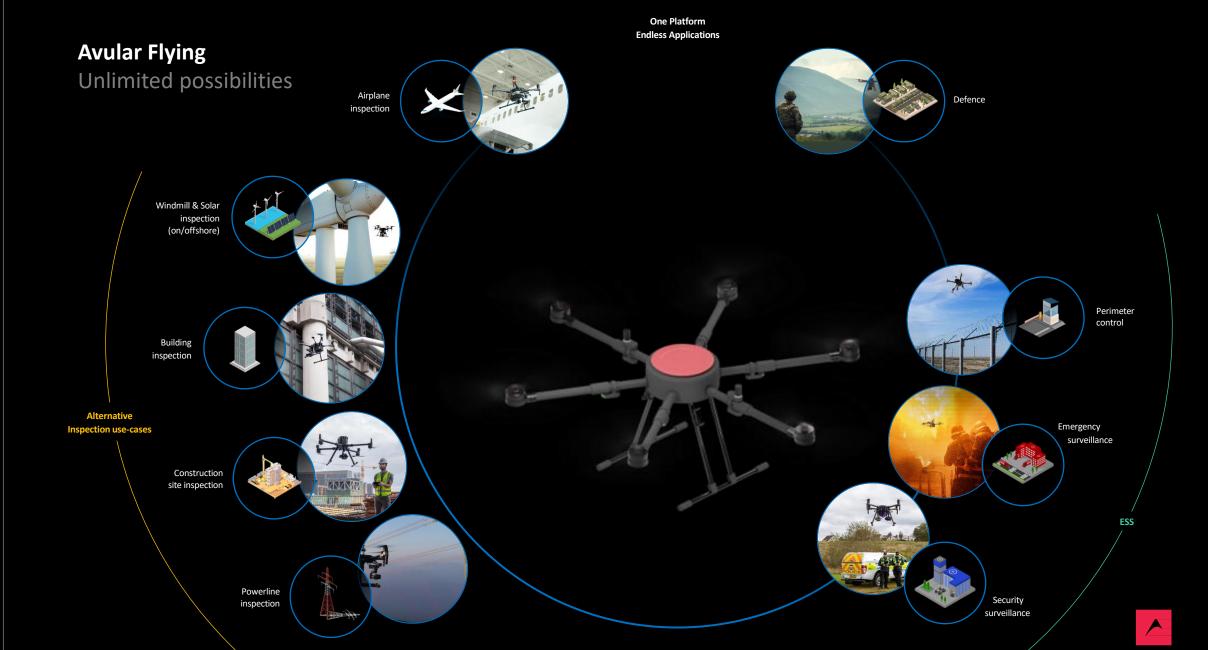


Our Vertex, a fully EUowned autonomous drone platform



Our Apex, the first step towards our flying family-of-systems





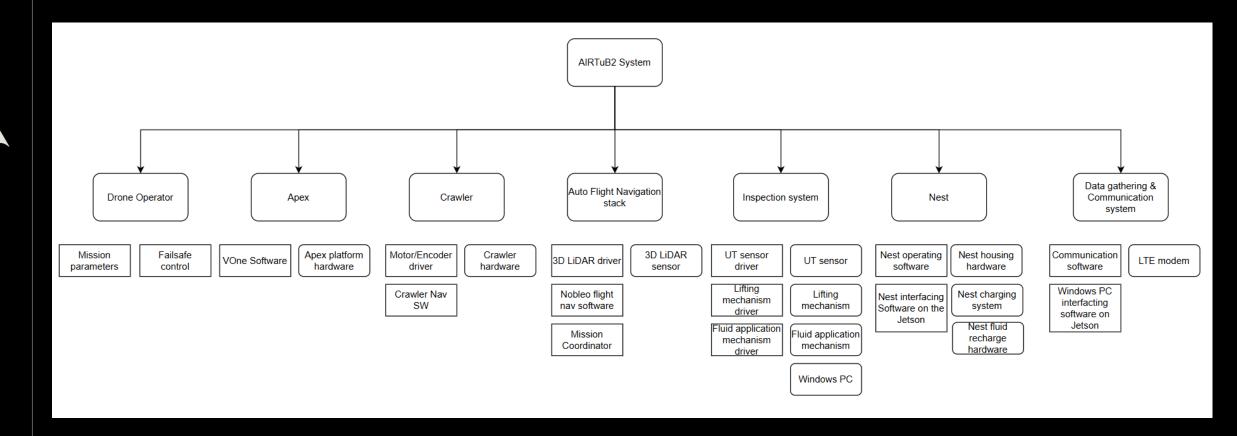
Avular's role in AIRTuB2

- Provide drone platform → Apex, hexacopter
- Automate & orchestrate complete mission workflow
- Automated failsafe behaviors
- Automated flight navigation
- Vision-based landing on dock

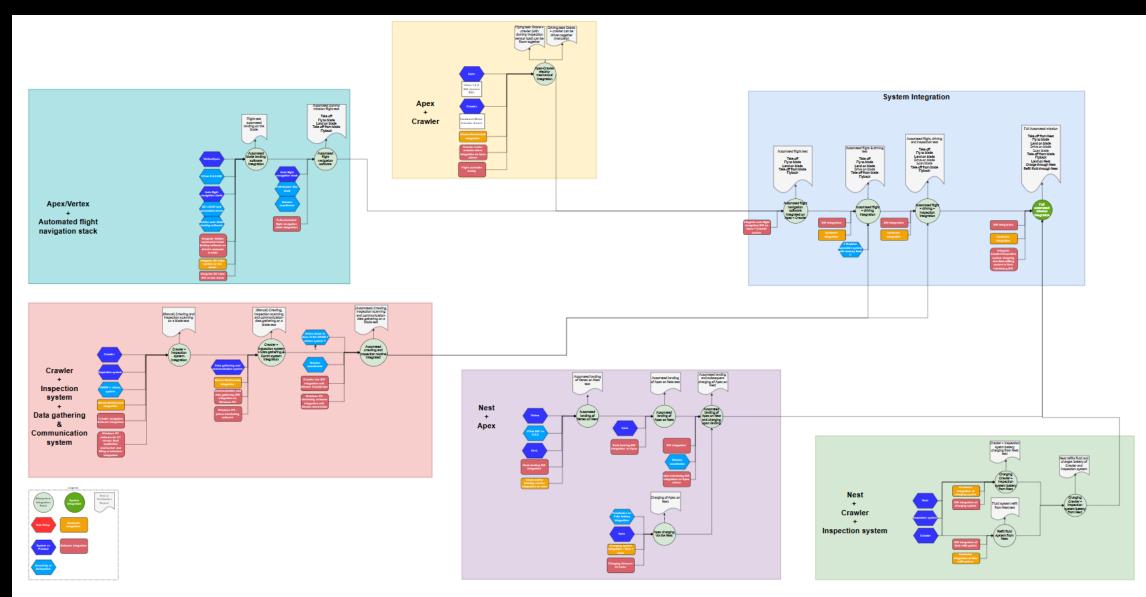


- Together with NLR oversee all flying related integration & testing
 - Certified facilities **>** experimental airborne systems
 - Terra Inspectioneering to operate the AIRTuB2 airborne system

AIRTuB2 - System of Systems

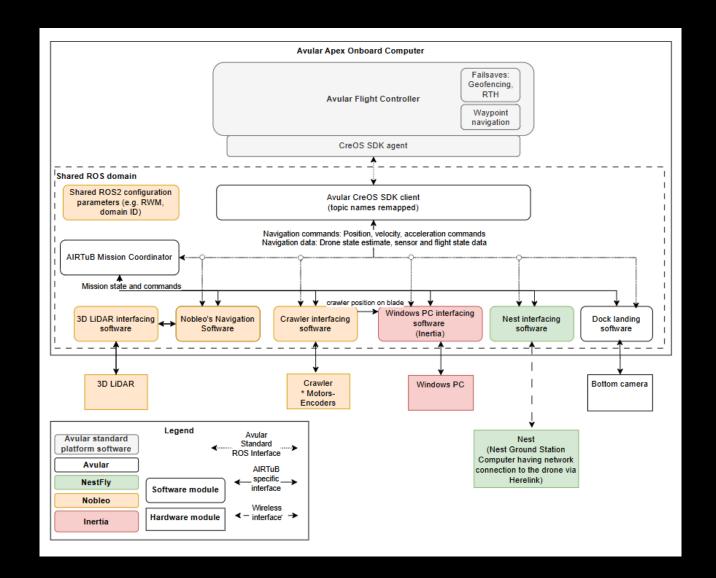


Strategic system integration - Prove reliability & <u>safety</u>



AIRTuB2 - Software modules

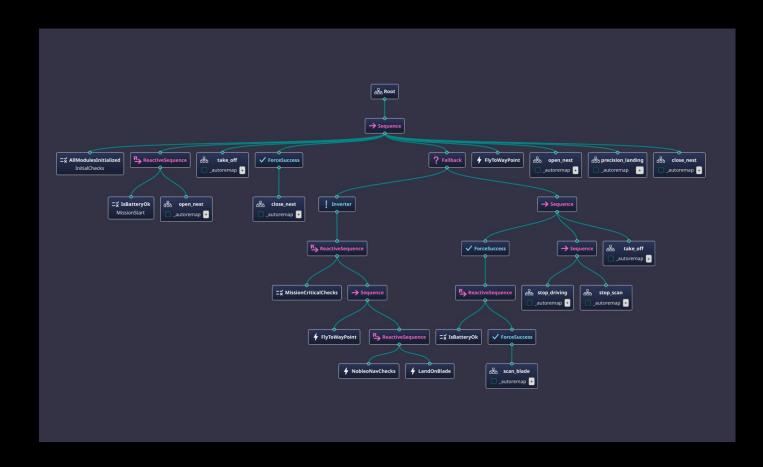
- Numerous software interfaces to orchestrate & track
- Inherently safe drone operation
- AIRTuB mission controls drone through an API
- Does not directly intervene with flight controls
- Always keeping drone stable



Mission Coordinator

Modular behavior tree design

- Easy to test sub-sets of the system in isolation
- Easily reconfigure based on integration insights



Drone specifications

- Set out to develop "system of systems" <u>under</u> 25 kg MTOW
- AIRTUB2 system now targeted ~35 kg MTOW
- Continuous development of Power Delivery system
 - To meet <u>safety</u> standards
 - Adapt to shifting scope
 - Continuous current of 150 A expected
 - Current peaks of >>200 A expected
- Avular required to <u>upgrade</u> platform
 - Upgrade to "Ultra high-density" battery pack(s)
 - Upgrade motor' thrust >> thrust-to-weight ratio
 - Tune Avular Flight Controller for MTOW
 - Verify inherent <u>safe</u> operation at MTOW

