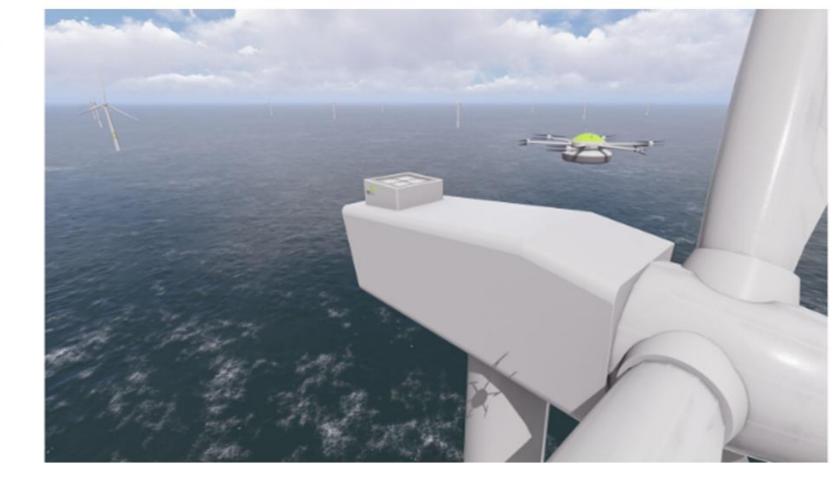




Annual event Fieldlab Zephyros AIRTuB-ROMI

28 november 2025 De KAAP - Vlissingen



Welcome





Stichting World Class Maintenance (WCM)

- Network for Smart & Sustainable Asset Management
- FME Industry organization for professional maintenance
- FME 🍀
- Foundation for open innovation, research, and education
- WCM's mission is to be the primary connecting and facilitating party for innovation
 in maintenance and asset management, thus contributing to major societal
 challenges such as the energy transition, labor market issues, mobility, circularity, etc.

World Class
Maintenance

World Class Assets

Solutions for societal challenges

 \triangleleft

<u>⊿</u>

Extensive experience in securing, developing, and disseminating knowledge in industrial environments





Rijen





Vlissingen

WCM projects bridge the "Valley of Death"



Technology Readiness Levels (TRL)

TRL9 Operations

TRL8 Active Commissioning

TRL7 Inactive Commissioning

TRL6 Large Scale

TRL5 Pilot Scale

TRL4 Bench Scale Research

TRL3 Proof of Concept

TRL2 Invention and Research

TRL1 Basic principles



























Why are you here? (what can you expect?):

Getting to know more about the AIRTuB-ROMI project:

- where do we stand with the project?
- what are our major challenges?
- How is the (large) team doing?

Updates on other related innovation projects:

- What more is happening out there?
- How does that look in practice

Inspiration to collaborate and join:

- gain new insights
- make new connections



Automated Inspection and Repair of Turbine Blades





Program

Time	Activity	Presenter(s)	Room
28-1	ov-25		
09:30–10:00	Arrival & Coffee		workshopruimte
10:00–10:10	Introduction into WCM Fieldlab Zephyros and Unmanned Maintenance Offshore	Ferry Visser and Jeroen Verschelling (WCM)	workshopruimte
10:10 - 10:30	Setting the Scene Digitale Noordzee	Steven Abdoelkhan & Martijn van Dijk (Rijkswaterstaat CIV)	workshopruimte
10:30–10:50	AIRTuB-ROMI Blade Sensors	Bart van de Hoek (WP1 leader AIRTuB-ROMI)	workshopruimte
10:50-11:10	AIRTuB-ROMI — Digital Twin, Dispatch Strategy & Dashboard (TNO)	Carel van Diggelen (TNO)	workshopruimte
11:10–11:30	AIRTuB-ROMI — Drone & Crawler Development, Integration & Lab Testing	Jos Gunsing, (WP3 Leader AIRTuB-ROMI)	workshopruimte
11:30	Coffee & move to demo zones		workshopruimte
11:40-13:30	Block 1 (presentations/demonstrations AIRTUB-ROMI)		demo zone - Kaap Loods
	AIRTUB-ROMI Drone: integration and certification	Paul Janssen (Avular) and Patrick Sloot (NLR)	demo zone - Kaap Loods
	AIRTuB-ROMI Crawler development	Paul Verhoeckx (Nobleo)	demo zone - Kaap Loods
	AIRTuB-ROMI Communications	Sabari Anbalagan (Inertia)	demo zone - Kaap Loods
	AIRTuB-ROMI Sliding Ultra Sonic probe	William Kramer (NLR)	demo zone - Kaap Loods
	AIRTUB-ROMI Docking station	Yves Lentfert (Nest-fly)	demo zone - Kaap Loods
	AIRTUB-ROMI Rolling Ultra Sonic probe	Roger Groves TU Delft)	demo zone - Kaap Loods
	AIRTuB-ROMI blade sensors (optical)	Jesse van Kempen (Tarucca)	demo zone - Kaap Loods
	AIRTuB-ROMI blade sensors (acoustic)	Malcolm Howe (Mistras)	demo zone - Kaap Loods
	AIRTuB-ROMI lifting device and fluid supply	Edward Mouw, Jos Gunsing (HZUAS and Scalda)	demo zone - Kaap Loods
12:30–13:30	Joint Lunch		workshopruimte
13:30- 15:00	Cross-project presentations part 1		workshopruimte
	NWO OTP project collaborative drones for offshore windturbine inspection	Sherry Wang (TU Delft)	workshopruimte
	Humanoids in offshore wind project development	Jeroen Verschelling (WCM)	workshopruimte
	X-ray blade inspections	Rita Raminhos (Spect X)	workshopruimte
	6G for offshore windturbine robotics	Marco Turini, Yohan Toh (TNO)	workshopruimte
	Blade sensor installation robot	Carel van Diggelen (TNO)	workshopruimte
	Complex tasks with drones	Ayham Alharbat (Saxion UAS)	workshopruimte
15:00-15:30	Coffee break		workshopruimte
15:00–16:30	Block 2 (information market blade inspection/repair technologies)		demo zone - Kaap Loods
	X-ray drone blade inspections	Rita Raminhos (Spect X)	demo zone - Kaap Loods
	Reblade/Teknos leading edge repair	Allan Bonde Jensen (Reblade/Teknos)	demo zone - Kaap Loods
	Complex tasks with drones	Ayham Alharbat (Saxion UAS)	demo zone - Kaap Loods
	Robotic drone transport hook	Thijs van 't Geloof (Ampelmann)	demo zone - Kaap Loods
	Lidar based mapping and position on a collision tolerant confined space drone	Steven Verver (Terra inspectioneering)	demo zone - Kaap Loods
16:30-17:00	Panel discussion	Various speakers, chairman: Ferry Visser	workshopruimte
17:00	Closing remarks & drinks	Ferry Visser and Jeroen Verschelling / WCM	workshopruimte



"Automated systems, robots and autonomous drones will replace the majority of human offshore maintenance tasks within the next decade."



"The biggest barrier to scaling drone and robot operations in offshore wind is not technology — it's regulation and certification."



"Continuous sensor-based monitoring will reduce unplanned turbine downtime more than any physical inspection method ever could."



"Data overload from advanced monitoring systems will become a greater challenge than the inspections themselves."

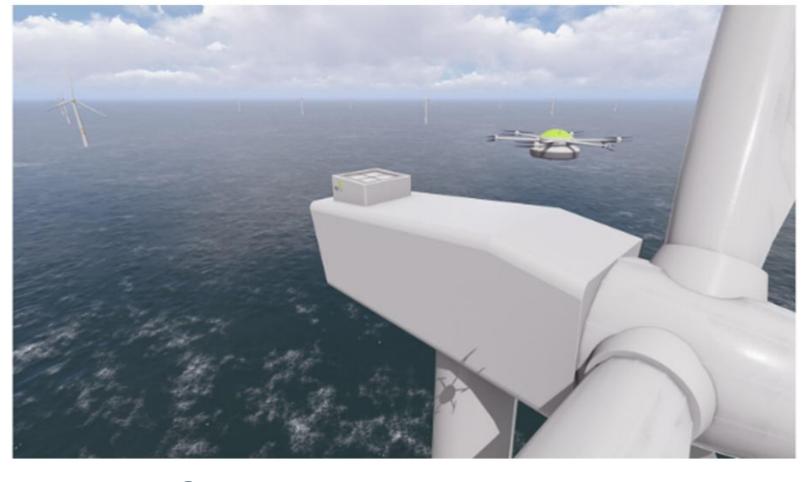






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Thank you and see you next time



